

Some rigidity results for minimal graphs over unbounded domains

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Sobolev inequalities in the Alps

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The Minimal Surface Equation (MSE)

Around 1762, *G.L. Lagrange* consider the following problem :

Find the graph of a smooth function $u = u(x, y)$, over a two-dimensional bounded and smooth domain Ω , having least area among all graphs that assume given values at the boundary of Ω .

Lagrange showed that, *if such a graph exists*, then u is a solution of

$$-\operatorname{div} \left(\frac{\nabla u}{\sqrt{1 + |\nabla u|^2}} \right) = 0 \quad \text{in } \Omega \quad (1)$$

- the graph of u is called *minimal graph*,
 - the above equation is named *Minimal Surface Equation (MSE)*,
 - (most likely) this was the beginning of the Calculus of Variations :
- (MSE) is the Euler-Lagrange equation associated with the area functional

$$\mathcal{A}(u) := \int_{\Omega} \sqrt{1 + |\nabla u|^2}. \quad (2)$$

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$$-\operatorname{div} \left(\frac{\nabla u}{\sqrt{1 + |\nabla u|^2}} \right) = 0 \quad \text{in } \Omega \subseteq \mathbb{R}^N,$$

- the l.h.s. of (MSE) is equal to $NH(x)$,
- $H(x)$ is the *the mean curvature* of the graph of u at the point $(x, u(x)) \in \mathbb{R}^{N+1}$.
- This fact was first observed, for $N = 2$, by J.B. Meusnier in 1776.
- A *minimal graph* provides a simple and natural example of "minimal submanifold" of dimension N .

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Bernstein's Theorem

Theorem (S.N. Bernstein, 1915)

Let $u \in C^2(\mathbb{R}^2)$ be a solution of the minimal surface equation (MSE)

$$-\operatorname{div} \left(\frac{\nabla u}{\sqrt{1 + |\nabla u|^2}} \right) = 0 \quad \text{on } \mathbb{R}^2 \quad (3)$$

Then u is an affine function, i.e.,

$$u(x, y) = \alpha x + \beta y + \gamma,$$

for some real constant α, β, γ .

The proof is based on a Liouville-type theorem for elliptic (*not uniformly elliptic*) operator, which holds true only in dimension 2.

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Theorem (S.N. Bernstein, 1915 - E. Hopf, 1950)

Let $a, b, c : \mathbb{R}^2 \rightarrow \mathbb{R}$ be functions such that the symmetric matrix :

$$\begin{pmatrix} a(x, y) & b(x, y) \\ b(x, y) & c(x, y) \end{pmatrix} \quad \text{is positive definite for every } (x, y) \in \mathbb{R}^2.$$

Let $u \in C^2(\mathbb{R}^2, \mathbb{R})$ be a solution of :

$$\begin{cases} a(x, y) \frac{\partial^2 u}{\partial x^2}(x, y) + 2b(x, y) \frac{\partial^2 u}{\partial x \partial y}(x, y) + c(x, y) \frac{\partial^2 u}{\partial y^2}(x, y) = 0 & \text{in } \mathbb{R}^2, \\ u(x, y) = o(\sqrt{x^2 + y^2}) & \text{as } \sqrt{x^2 + y^2} \rightarrow +\infty. \end{cases} \quad (4)$$

Then u is a constant function.

Proof of Bernstein's Theorem in \mathbb{R}^2

A direct calculation shows that the smooth functions

$$v_1 = \arctan\left(\frac{\partial u}{\partial x}\right), \quad v_2 = \arctan\left(\frac{\partial u}{\partial y}\right)$$

are *bounded solutions*, on \mathbb{R}^2 , of the equation :

$$\left(1 + \left(\frac{\partial u}{\partial y}\right)^2\right) \frac{\partial^2 v}{\partial x^2} - 2 \frac{\partial u}{\partial x} \frac{\partial u}{\partial y} \frac{\partial^2 v}{\partial x \partial y} + \left(1 + \left(\frac{\partial u}{\partial x}\right)^2\right) \frac{\partial^2 v}{\partial y^2} = 0.$$

An application of the previous Theorem with the matrix

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$$\begin{aligned} \lambda_1 = 1, \quad \lambda_2 = 1 + |\nabla u|^2 \\ \Downarrow \\ v_1, v_2 \text{ are constant} \implies \nabla u = \text{const.} \\ \Downarrow \\ u \text{ is an affine function.} \end{aligned}$$

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The Bernstein property (BP)

The natural problem of whether the only solutions of the minimal surface equation on \mathbb{R}^N , $N \geq 3$, are first degree polynomials became known as *Bernstein's problem (or Bernstein property)* .

This problem resisted for a half-century and was solved thanks to the combined efforts of some giants of mathematics of the XX century.

The Bernstein property (BP) is true in :

- \mathbb{R}^3 , *E. De Giorgi (1965)*
- \mathbb{R}^4 , *F.J. Almgren (1966)*
- \mathbb{R}^N , for $N \leq 7$, *J. Simons (1968)*

The proofs are based on the *deep connection* between minimal graphs defined over \mathbb{R}^N and minimal (*area-minimizing*) cones in \mathbb{R}^N .

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Failure of Bernstein property (BP)

The Bernstein property fails in \mathbb{R}^N , for any $N \geq 8$.

In 1969, E. Bombieri, E. De Giorgi and E. Giusti, settled Bernstein's problem proving the *existence of a non-affine solution* of the minimal surface equation (MSE) in \mathbb{R}^N , for any $N \geq 8$.

Their (amazing) proof relies on the existence of a minimal, and area-minimizing cone (*Simons' cone*)

$$C_{4,4} := \{(x, y) \in \mathbb{R}^4 \times \mathbb{R}^4 \quad : \quad |x|^2 < |y|^2\}$$

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Moser's Theorem

Theorem (J. Moser, 1961)

Let $N \geq 2$ and $u \in C^2(\mathbb{R}^N)$ be a solution of :

$$\begin{cases} -\operatorname{div} \left(\frac{\nabla u}{\sqrt{1+|\nabla u|^2}} \right) = 0 & \text{on } \mathbb{R}^N, \\ \nabla u \in L^\infty(\mathbb{R}^N). \end{cases} \quad (5)$$

Then u is an affine function.

Proof of Moser's Theorem

- Since u is smooth, by differentiating the (MSE) we get

$$-\operatorname{div}(A(x)\nabla u_j) = 0 \quad \text{on} \quad \mathbb{R}^N \quad (6)$$

where u_j denotes the partial derivative $\frac{\partial u}{\partial x_j}$, for any $j = 1, \dots, N$, and $A = (a_{hk})$ is the real symmetric matrix whose entries are given by :

$$a_{hk} = a_{hk}(x) := \frac{\delta_{hk}}{(1 + |\nabla u|^2)^{\frac{1}{2}}} - \frac{u_h u_k}{(1 + |\nabla u|^2)^{\frac{3}{2}}}. \quad (7)$$

- $\lambda_{\min}(A) = \frac{1}{(1 + |\nabla u|^2)^{\frac{3}{2}}}$ and $\lambda_{\max}(A) = \frac{1}{(1 + |\nabla u|^2)^{\frac{1}{2}}}$.
- $\nabla u \in L^\infty(\mathbb{R}^N) \implies$ equation (6) is uniformly elliptic on \mathbb{R}^N .
- The classic Liouville-type theorem $\implies u_j = \text{const.} \implies u$ affine.

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- $\nabla u \in L^\infty(\mathbb{R}^N) \implies$ equation (6) is uniformly elliptic on \mathbb{R}^N .
- The classic Liouville-type theorem $\implies u_j = \text{const.} \implies u$ affine.

The theorem of Bombieri and Giusti

Theorem (E. Bombieri, E. Giusti, 1972)

Let $N \geq 2$ and $u \in C^2(\mathbb{R}^N)$ be a solution of

$$-\operatorname{div} \left(\frac{\nabla u}{\sqrt{1 + |\nabla u|^2}} \right) = 0 \quad \text{on } \mathbb{R}^N,$$

such that $N-1$ partial derivatives of u are bounded on \mathbb{R}^N .
Then u is an affine function.

To prove their result, E. Bombieri and E. Giusti, demonstrate

- a new Harnack inequality for uniformly elliptic equations on minimal surfaces (oriented boundary of least area).
- if $N - 1$ partial derivatives of u are bounded on \mathbb{R}^N , then u has bounded gradient on \mathbb{R}^N .
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A sharp Bernstein-type result

Theorem (A.F., 2018)

Let $N \geq 8$ and $u \in C^2(\mathbb{R}^N)$ be a solution of

$$-\operatorname{div} \left(\frac{\nabla u}{\sqrt{1 + |\nabla u|^2}} \right) = 0 \quad \text{on } \mathbb{R}^N,$$

such that

$N - 7$ partial derivatives of u are bounded on one side
(not necessarily the same).

Then u is an affine function.

The theorem is sharp.

Its proof is completely different from the one of Bombieri and Giusti.

A rigidity result on half-spaces

Theorem (A.F., 2022)

Assume $N \geq 2$ and let Σ be an open affine half-space of \mathbb{R}^N . If $u \in C^2(\overline{\Sigma})$ is a solution of

$$\begin{cases} -\operatorname{div} \left(\frac{\nabla u}{\sqrt{1+|\nabla u|^2}} \right) = 0 & \text{in } \Sigma, \\ u > 0 & \text{in } \Sigma, \\ u = 0 & \text{in } \partial\Sigma, \end{cases}$$

then u is an affine function.

The proof is based on the following new rigidity result for entire minimal graphs.

Rigidity on the entire space I

Theorem (A.F., 2022)

Assume $N \geq 2$ and let $v \in C^2(\mathbb{R}^N)$ be a solution of the minimal surface equation

$$-\operatorname{div} \left(\frac{\nabla v}{\sqrt{1 + |\nabla v|^2}} \right) = 0 \quad \text{on } \mathbb{R}^N$$

If for some $a, b \in \mathbb{R}$ the set $\{x \in \mathbb{R}^N : v(x) > a|x| + b\}$ is contained in an open affine half-space of \mathbb{R}^N , then u is an affine function.

The same conclusion remains true if the above assumption is replaced by:
for some $a', b' \in \mathbb{R}$ the set $\{x \in \mathbb{R}^N : v(x) < a'|x| + b'\}$ is contained in an open affine half-space of \mathbb{R}^N .

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Proof of the main result on half-spaces

- W.l.o.g we may and do suppose that $\Sigma = \{x \in \mathbb{R}^N : x_N > 0\}$
- Let $v : \mathbb{R}^N \rightarrow \mathbb{R}$ be the odd extension of u with respect to $\partial\Sigma$
- Thanks to the homogeneous Dirichlet boundary condition satisfied by u , it is easily seen that v is an *entire minimal graph* such that

$$\{x \in \mathbb{R}^N : v(x) > 0\} = \{x \in \mathbb{R}^N : x_N > 0\}$$

- Theorem 1 with $a = b = 0 \implies v$ is affine.

The latter implies that u is an affine function.

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A rigidity result on the entire space II

Another interesting consequence of Theorem 1 is the following

Theorem II (A.F., 2022)

Assume $N \geq 2$ and let $v \in C^2(\mathbb{R}^N)$ be a solution of the minimal surface equation

$$-\operatorname{div} \left(\frac{\nabla v}{\sqrt{1 + |\nabla v|^2}} \right) = 0 \quad \text{on } \mathbb{R}^N$$

If for some $a, b \in \mathbb{R}$ the set $\{x \in \mathbb{R}^N : v(x) > a|x| + b\}$ contains an open affine half-space of \mathbb{R}^N , then u is an affine function.

The same conclusion remains true if the above assumption is replaced by:

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Rigidity on the entire space II : proof

By assumption, the set $\{x \in \mathbb{R}^N : v(x) > a|x| + b\}$ contains an open affine half-space Σ .

Therefore, the set $\{x \in \mathbb{R}^N : v(x) < a|x| + b\}$ is contained in the open affine half-space $\Sigma' := \mathbb{R}^N \setminus \overline{\Sigma}$ and so v must be an affine function thanks to Theorem 1.

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Let us recall the following well-know Liouville-type Theorem for entire minimal graphs :

Theorem (E. Bombieri, E. De Giorgi, M.Miranda, 1969)

Let v be an entire minimal graphs such that

$$v(x) \geq -K(1 + |x|) \quad \forall x \in \mathbb{R}^N,$$

for some $K \geq 0$. Then v is an affine function.

Theorem (A.F., 2022)

Let Σ be an open affine half-space and let v be an entire minimal graphs such that

$$v(x) \geq -K(1 + |x|) \quad \forall x \in \Sigma,$$

for some $K \geq 0$. Then v is an affine function.

Rigidity on the entire space I : sketch of proof

- W.l.o.g we may and do suppose that

$$\{x \in \mathbb{R}^N : v(x) > a|x| + b\} \subset \{x \in \mathbb{R}^N : x_N > 0\} =: \Sigma$$

- $u = v - v(0)$ is again an entire solution to (MSE) with $u(0) = 0$.
- Let U be the subgraph of u and let U_j be the one of the function u_j defined by

$$u_j(x) = \frac{u(jx)}{j}, \quad x \in \mathbb{R}^N, \quad j \geq 1.$$

Since u and u_j are solutions of the (MSE) on \mathbb{R}^N , then

U_j are non-trivial minimal sets of \mathbb{R}^{N+1} with $0 \in \partial U_j$

Also observe that $U_j := \frac{U}{j}$.

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Rigidity on the entire space I : sketch of proof

- By a classical *blow down* procedure, a subsequence of U_j (still denoted by U_j) converges to a minimal cone $C \subset \mathbb{R}^{N+1}$, with vertex at the origin of \mathbb{R}^{N+1} and s.t. $0 \in \partial C$.
(C is usually called a *blow down of U*).

Recall that the blow down procedure also implies :

$$C \text{ half-space} \implies U \equiv C$$

- Hence, (by results of M. Miranda), C is itself a subgraph of a generalized solution to the minimal surface equation $h : \mathbb{R}^N \rightarrow [-\infty, +\infty]$ and the sets

$$P = \{x \in \mathbb{R}^N : h(x) = +\infty\}, \quad N = \{x \in \mathbb{R}^N : h(x) = -\infty\}$$

are both minimal cones of \mathbb{R}^N .

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- $P = \emptyset$.

Suppose for contradiction that P is not-empty, then P is a minimal cone in \mathbb{R}^N , with vertex at the origin of \mathbb{R}^N (since C is a minimal cone with vertex at the origin of \mathbb{R}^{N+1}).

- P is contained in Σ . Indeed, if $p \in P$, then there exists an integer $j > 1$ such that $u_j(p) > |v(0)| + |a||p| + |b|$ and so

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that is, $jp \in \{x \in \mathbb{R}^N : v(x) > a|x| + b\}$. Therefore, $jp \in \Sigma$ and so also $p \in \Sigma$.

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$$\Sigma \times \mathbb{R} = P \times \mathbb{R} \subset C$$

by construction of C and definition of P .

Therefore, $C \equiv \Sigma \times \mathbb{R}$ and so $U = C$.

But $U = C \equiv \Sigma \times \mathbb{R}$ implies that ∂U is a vertical hyperplane, contradicting the fact ∂U is the graph of the function u .

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This and the definition of u_j provide the following estimate

$$\sup_{B(0,j)} u \leq \mathcal{K}j \quad (8)$$

for some constant $\mathcal{K} > 0$.

- On the other hand, the celebrated gradient estimate of E. Bombieri, E. De Giorgi, M.Miranda, (1969) tells us that

$$\forall x \in \mathbb{R}^N, \forall R > 0, \quad |\nabla u(x)| \leq C_1 \exp \left[C_2 \left(\frac{\sup_{B(x,R)} u - u(x)}{R} \right) \right] \quad (9)$$

where C_1, C_2 are constants depending only on the dimension N .

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Perimeter of measurable sets (De Giorgi 1954)

X a Lebesgue measurable set of $\mathbb{R}^N, N \geq 1$.

The *Perimeter* of X in an open set $\Omega \subset \mathbb{R}^N$ is the *total variation of the distributional gradient of $\mathbf{1}_X$* in Ω , i.e.,

$$\text{Per}(X, \Omega) := \sup \left\{ \int_{\Omega} \text{div} g : g \in C_c^1(\Omega, \mathbb{R}^N), \|g\|_{\infty} \leq 1 \right\} \quad (10)$$

X has *locally finite perimeter* in Ω if

$$\text{Per}(X, A) < +\infty, \quad \forall \text{ open set } A \subset\subset \Omega. \quad (11)$$

X has *locally finite perimeter* in Ω if and only if $\mathbf{1}_X \in BV_{loc}(\Omega)$.

Notation : $\text{Per}(X, \Omega) = \int_{\Omega} |D\mathbf{1}_X|$.

If X is smooth set of \mathbb{R}^N , then $\text{Per}(X, \Omega) = \mathcal{H}^{N-1}(\partial X \cap \Omega)$.

Perimeter of measurable sets (De Giorgi 1954)

X a Lebesgue measurable set of $\mathbb{R}^N, N \geq 1$.

The *Perimeter* of X in an open set $\Omega \subset \mathbb{R}^N$ is the *total variation of the distributional gradient of $\mathbf{1}_X$* in Ω , i.e.,

$$\text{Per}(X, \Omega) := \sup \left\{ \int_{\Omega} \text{div} g : g \in C_c^1(\Omega, \mathbb{R}^N), \|g\|_{\infty} \leq 1 \right\} \quad (10)$$

X has *locally finite perimeter* in Ω if

$$\text{Per}(X, A) < +\infty, \quad \forall \text{ open set } A \subset\subset \Omega. \quad (11)$$

X has *locally finite perimeter* in Ω if and only if $\mathbf{1}_X \in BV_{loc}(\Omega)$.

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Minimal sets

$E \subset \mathbb{R}^N$ is a (local) minimal set in Ω if, for every open set $A \subset\subset \Omega$,

$$Per(E, A) < +\infty \quad (12)$$

$$Per(E, A) \leq Per(X, A), \quad \forall X \text{ with } X \Delta E \subset A \quad (13)$$